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Optimal Relativities and Transition Rules of a Bonus-Malus System

Chong It Tan, ASA, CERA Nanyang Business School, Singapore

Co-authors

- Dr Jackie Li
 - Nanyang Business School, Singapore
- Dr Johnny Siu-Hang Li University of Waterloo, Canada
- Dr Uditha Balasooriya Nanyang Business School, Singapore



Agenda

- Bonus-Malus System (BMS)
- Motivation
- > 3 implications; 2 inadequacy scenarios
- Optimal relativities
- Effectiveness of transition rules
- Varying transition rules
- Numerical illustrations
- Future research



Bonus-Malus System (BMS)

- BMS levels
- Transition rules
- ➤ no claim -> bonus (↓ BMS levels)
- > claim -> malus (↑ BMS levels)
- Relativities
 - = premium adjustment coefficients



Taylor (1997):

justifiable BMS relativities need to recognize the differentiation of underlying claim frequencies by experience, but only to the extent that this differentiation has not been recognized within the base premiums.



Implication 1:

deal with heterogeneity within each risk class but not the heterogeneity between different risk classes

modeling of unobserved heterogeneity (see, e.g., Lemaire, 1995; Denuit et al., 2007)



Implication 2:

a priori information should be incorporated into the determination of optimal relativity

Taylor (1997): simulation approach

> Pitrebois et al. (2003): analytical formula



Implication 3:

the average *a priori* expected claim frequencies of BMS levels should exhibit as little variations as possible

> not addressed in previous studies



Inadequacy scenario 1:

Identical optimal relativities regardless of *a priori* expected claim frequencies

- Pitrebois et al. (2003): 2 sets of optimal relativities for urban/rural drivers
- It the heterogeneity between different risk classes are dealt with separately, contradictory with implication 1



Inadequacy scenario 2:

Identical transition rules regardless of current levels occupied



 Θ = unobserved heterogeneity (true relative premium) r_L = relativity for level *L* (actual relative premium) Λ = unknown *a priori* expected claim frequency $\bar{\lambda}$ = average expected claim frequency



Norberg (1976): without a priori classification $\min \mathbb{E}\left[\left(\bar{\lambda}\Theta - \bar{\lambda}r_L\right)^2\right] \equiv \min \mathbb{E}[(\Theta - r_L)^2]$ Pitrebois et al. (2003): analytical formula $\min \mathbb{E}[(\Theta - r_L)^2]$

The minimization of expected squared difference between true relative premium and actual relative premium does not take into account the base premiums



Our new objective function

 $\min \mathbb{E}[(\Lambda \Theta - \Lambda r_L)^2]$

by incorporating the amount of base premiums, the obtained solution would partially address inadequacy scenario 1.

Coene and Doray (1996):

financial equilibrium constraint $E(r_L) = 1$



Langrangian method:

$$\mathcal{L}(r,\alpha) = \mathbb{E}\left[(\Lambda\Theta - \Lambda r_L)^2\right] + \alpha(E(r_L) - 1)$$

Solution: $\alpha = \frac{\left(\sum_{\ell=1}^{j} \frac{\mathbb{E}\left[\Lambda^{2}\Theta \left|L=\ell\right] \operatorname{Pr}(L=\ell)\right]}{\mathbb{E}\left[\Lambda^{2} \left|L=\ell\right]}\right) - 1}{\sum_{\ell=1}^{j} \frac{\Pr(L=\ell)}{2\mathbb{E}\left[\Lambda^{2} \left|L=\ell\right]}}{r_{\ell}} \frac{\Gamma(L=\ell)}{\mathbb{E}\left[\Lambda^{2} \left|L=\ell\right]} - \frac{\alpha}{2\mathbb{E}\left[\Lambda^{2} \left|L=\ell\right]}}$ A 2014 CIA

Effectiveness of transition rules

Pitrebois et al. (2003): interaction of a priori and a posteriori ratings

$$\mathbb{E}[\Lambda|L=\ell]$$

Our contribution:

$$\mathbb{V}[\Lambda] = \mathbb{E}\big[\mathbb{V}[\Lambda|L]\big] + \mathbb{V}\big[\mathbb{E}[\Lambda|L]\big]$$

Implication 3 seek to minimize the 2nd component / maximize the 1st component

effectiveness, $\tau_{\text{rule}} = \frac{\mathbb{E}[\mathbb{V}[\Lambda|L]]}{\mathbb{V}[\Lambda]}$



Varying transition rules

To address inadequacy scenario 2, introduce varying rules dependent on the current level occupied.

Effective level transition for drivers staying in level ℓ and make k claims in current year = $t_{\ell,k}$ malus transition:

$$t_{\ell,k} \ge 0, t_{\ell_2,k} \le t_{\ell_1,k}$$
 for $k \ge 1, \ell_2 \ge \ell_1$

bonus transition:

$$t_{\ell,0} \leq 0, \left| t_{\ell_2,k} \right| \geq \left| t_{\ell_1,k} \right| \operatorname{for} \ell_2 \geq \ell_1$$



Numerical illustrations

$$t_{\ell,0} = \begin{cases} 0, & \text{for } \ell = 1\\ -1, & \text{for } 2 \leq \ell \leq \left\lceil \frac{j}{2} \right\rceil + 1\\ -2, & \text{for } \ell > \left\lceil \frac{j}{2} \right\rceil + 1 \end{cases}$$
$$t_{\ell,k} = \begin{cases} \min\left[j - \ell, \max\left[k, \left\lceil \frac{j - \ell}{p} \times k \right\rceil\right]\right], & \text{for } k \geq 1, \ell < j\\ 0, & \text{for } k \geq 1, \ell = j \end{cases}$$



TABLE 1

Transition rules for the simple rules of -1/+2 (varying rules with p=4)

	Level occupied if					
Starting level	0	1	2	3	≥ 4	
9	8(7)	9 (9)	9 (9)	9 (9)	9(9)	
8	7(6)	9 (9)	9 (9)	9 (9)	9 (9)	
7	6(5)	9 (8)	9 (9)	9 (9)	9(9)	
6	5(5)	8 (7)	9 (8)	9(9)	9(9)	
5	4 (4)	7(6)	9 (7)	9 (8)	9 (9)	
4	3(3)	6(6)	8 (7)	9 (8)	9(9)	
3	2(2)	5(5)	7(6)	9 (8)	9 (9)	
2	1 (1)	4 (4)	6(6)	8 (8)	9 (9)	
1	1 (1)	3 (3)	5(5)	7(7)	9 (9)	



Transition rules for the simple rules of -1/+3 (varying rules with p=3)

Starting level	0	Level occ 1 claims are	cupied if 2 reported	≥ 3
9 8 7 6 5 4	8 (7) 7 (6) 6 (5) 5 (5) 4 (4) 3 (3)	9 (9) 9 (9) 9 (8) 9 (7) 8 (7) 7 (6)	9 (9) 9 (9) 9 (9) 9 (9) 9 (8) 9 (8) 9 (8) 9 (8)	9 (9) 9 (9) 9 (9) 9 (9) 9 (9) 9 (9) 9 (9) 9 (9)
3 2 1	$ \begin{array}{c} 2 (2) \\ 1 (1) \\ 1 (1) \end{array} $	$ \begin{array}{c} 6 \\ (5) \\ 5 \\ (5) \\ 4 \\ (4) \end{array} $	9 (7) 8 (7) 7 (7)	$ \begin{array}{c} 9 \\ (9) \\ 9 \\ (9) \\ 9 \\ (9) \\ 9 \\ (9) \end{array} $



TABLE 3 Interaction between a priori and a posteriori ratemakings								
	-1/+2		Varying $p = 4$		-1/+3		Varying $p = 3$	
level ℓ	$\Pr\left[L=\ell\right]$	$\mathbb{E}\left[\Lambda L=\ell\right]$						
9	2.87%	19.26%	0.70%	21.35%	5.06%	18.02%	1.19%	20.10%
8	2.35%	18.27%	0.54%	19.23%	4.09%	17.21%	1.12%	18.07%
7	2.31%	17.37%	1.26%	18.73%	4.17%	16.36%	2.83%	17.38%
6	2.31%	16.78%	2.34%	17.34%	3.94%	15.90%	2.14%	16.59%
5	3.20%	16.01%	4.24%	16.70%	3.72%	15.58%	5.51%	16.28%
4	3.37%	15.68%	4.17%	16.17%	7.29%	14.83%	9.18%	15.25%
3	8.09%	14.90%	8.97%	15.16%	6.20%	14.70%	7.57%	15.04%
2	6.84%	14.77%	7.44%	14.97%	5.33%	14.59%	6.34%	14.87%
1	68.66%	13.97%	70.34%	14.03%	60.21%	13.87%	64.13%	13.97%



Effectiveness of transition rules						
Transition rules	$ au_{ m rule}$					
-1/+2	93.87%					
varying $p = 4$	94.74%					
-1/+3	94.56%					
varying $p = 3$	95.18%					





	-1/+2		Varying $p = 4$		-1/+3		Varying $p = 3$	
level ℓ	r_{ℓ}	$r_{\ell}^{\mathrm{unconstrained}}$	r_ℓ	$r_{\ell}^{\mathrm{unconstrained}}$	r_{ℓ}	$r_\ell^{ m unconstrained}$	r_{ℓ}	$r_{\ell}^{\mathrm{unconstraine}}$
9	266.57%	261.07%	420.41%	419.11%	233.67%	227.73%	293.04%	288.85%
8	235.37%	229.27%	317.11%	315.62%	205.54%	199.03%	230.71%	225.56%
7	207.95%	201.22%	307.54%	305.95%	176.56%	169.34%	211.92%	206.36%
6	188.51%	181.29%	234.82%	233.11%	159.35%	151.70%	183.85%	177.74%
5	162.42%	154.47%	215.07%	213.20%	146.58%	138.59%	173.05%	166.69%
4	150.04%	141.74%	186.85%	184.91%	115.41%	106.55%	133.57%	126.30%
3	118.70%	109.49%	127.08%	125.08%	109.31%	100.29%	124.15%	116.67%
2	112.85%	103.46%	118.27%	116.22%	103.93%	94.75%	116.18%	108.51%
1	72.92%	62.35%	69.43%	67.10%	66.34%	56.11%	70.86%	62.08%
$\mathbb{E}\left[r_L\right]$	100%	90.20%	100%	97.79%	100%	90.68%	100%	91.90%

TABLE 5Optimal relativities for the BMS



Future research

- how the varying extent of a priori classification affects the choice of sufficiently effective transition rules
- Gilde and Sundt (1989): linear relativities



Q&A



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