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Optimal Relativities and Transition Rules of a Bonus-Malus System

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Agenda

- Bonus-Malus System (BMS)
- **Motivation**
- 3 implications; 2 inadequacy scenarios
- Optimal relativities
- Effectiveness of transition rules
- Varying transition rules
- Numerical illustrations
- Future research

Bonus-Malus System (BMS)

- BMS levels
- Transition rules
- no claim -> bonus (↓ BMS levels)
- claim -> malus (↑ BMS levels)
- Relativities
	- = premium adjustment coefficients

Taylor (1997):

 \triangleright justifiable BMS relativities need to recognize the differentiation of underlying claim frequencies by experience, but only to the extent that this differentiation has not been recognized within the base premiums.

Implication 1:

deal with heterogeneity within each risk class but not the heterogeneity between different risk classes

 modeling of unobserved heterogeneity (see, e.g., Lemaire, 1995; Denuit et al., 2007)

Implication 2:

a priori information should be incorporated into the determination of optimal relativity

 \triangleright Taylor (1997): simulation approach

 \triangleright Pitrebois et al. (2003): analytical formula

Implication 3:

the average *a priori* expected claim frequencies of BMS levels should exhibit as little variations as possible

 \triangleright not addressed in previous studies

Inadequacy scenario 1:

Identical optimal relativities regardless of *a priori* expected claim frequencies

- \triangleright Pitrebois et al. (2003): 2 sets of optimal relativities for urban/rural drivers
- \triangleright the heterogeneity between different risk classes are dealt with separately, contradictory with implication 1

Inadequacy scenario 2:

Identical transition rules regardless of current levels occupied

 Θ = unobserved heterogeneity (true relative premium) r_L = relativity for level L (actual relative premium) Λ = unknown *a priori* expected claim frequency $\bar{\lambda}$ = average expected claim frequency

Norberg (1976): without a priori classification min $\mathbb{E}\left[\left(\bar{\lambda}\Theta - \bar{\lambda}r_L\right)^2\right] \equiv \min \mathbb{E}[(\Theta - r_L)^2]$ Pitrebois et al. (2003): analytical formula min $\mathbb{E}[(\Theta-r_L)^2]$

 \triangleright the minimization of expected squared difference between true relative premium and actual relative premium does not take into account the base premiums

Our new objective function

min $\mathbb{E}[(\Lambda \Theta - \Lambda r_I)^2]$

 \triangleright by incorporating the amount of base premiums, the obtained solution would partially address inadequacy scenario 1.

Coene and Doray (1996):

financial equilibrium constraint $E(r_L) = 1$

Langrangian method:

$$
\mathcal{L}(r,\alpha) = \mathbb{E}[(\Lambda \Theta - \Lambda r_L)^2] + \alpha(E(r_L) - 1)
$$

Solution:

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$$
\alpha = \frac{\left(\sum_{\ell=1}^{j} \frac{\mathbb{E}[A^2 \Theta | L = \ell] \Pr(L = \ell)}{\mathbb{E}[A^2 | L = \ell]}\right) - 1}{\sum_{\ell=1}^{j} \frac{\Pr(L = \ell)}{2\mathbb{E}[A^2 | L = \ell]}}{\sum_{\ell=1}^{j} \frac{\Pr(L = \ell)}{2\mathbb{E}[A^2 | L = \ell]}} \frac{\alpha}{\exp(\alpha/2) \exp(\alpha/2)} \frac{\Gamma(\alpha/2)}{\Gamma(\alpha/2)} \frac{\Gamma(\alpha/
$$

Effectiveness of transition rules

Pitrebois et al. (2003): interaction of a priori and a posteriori ratings

$$
\mathbb{E}[\Lambda|L=\ell]
$$

Our contribution:

$$
\mathbb{V}[\Lambda] = \mathbb{E}[\mathbb{V}[\Lambda|L]] + \mathbb{V}[\mathbb{E}[\Lambda|L]]
$$

Implication 3 seek to minimize the $2nd$ component / maximize the 1st component

effectiveness, $\tau_{\text{rule}} = \frac{\mathbb{E}[\mathbb{V}[\Lambda|L]]}{\mathbb{V}[\Lambda]}\$

Varying transition rules

To address inadequacy scenario 2, introduce varying rules dependent on the current level occupied.

Effective level transition for drivers staying in level ℓ and make k claims in current year = $t_{\ell,k}$ malus transition:

$$
t_{\ell,k} \ge 0, t_{\ell_2,k} \le t_{\ell_1,k}
$$
 for $k \ge 1, \ell_2 \ge \ell_1$

bonus transition:

$$
t_{\ell,0} \le 0, |t_{\ell_2,k}| \ge |t_{\ell_1,k}| \text{ for } \ell_2 \ge \ell_1
$$

Numerical illustrations

$$
t_{\ell,0} = \begin{cases} 0, & \text{for } \ell = 1 \\ -1, & \text{for } 2 \le \ell \le \lceil \frac{j}{2} \rceil + 1 \\ -2, & \text{for } \ell > \lceil \frac{j}{2} \rceil + 1 \end{cases}
$$
\n
$$
t_{\ell,k} = \begin{cases} \min\left[j - \ell, \max\left[k, \lceil \frac{j - \ell}{p} \times k \rceil\right]\right], & \text{for } k \ge 1, \ell < j \\ 0, & \text{for } k \ge 1, \ell = j \end{cases}
$$

TABLE 1

TRANSITION RULES FOR THE SIMPLE RULES OF $-1/+2$ (VARYING RULES WITH $p = 4$)

TRANSITION RULES FOR THE SIMPLE RULES OF $-1/+3$ (VARYING RULES WITH $p=3$)

	$-1/+2$		Varying $p = 4$		$-1/+3$		Varying $p=3$	
level ℓ	r_{ℓ}	$_{r}$ unconstrained r_{ℓ}	r_{ℓ}	$r_\ell^{\rm unconstrained}$	r_{ℓ}	$r_\ell^{\rm unconstrained}$	r_{ℓ}	$_{r}$ unconstrained
9	266.57%	261.07%	420.41\%	419.11\%	233.67%	227.73%	293.04%	288.85%
8	235.37%	229.27\%	317.11\%	315.62\%	205.54\%	199.03%	230.71\%	225.56%
	207.95%	201.22%	307.54\%	305.95%	176.56%	169.34%	211.92%	206.36%
6	188.51\%	181.29%	234.82\%	233.11\%	159.35%	151.70%	183.85%	177.74%
5	162.42%	154.47%	215.07%	213.20%	146.58%	138.59%	173.05%	166.69%
4	150.04%	141.74%	186.85%	184.91%	115.41\%	106.55%	133.57%	126.30%
3	118.70%	109.49%	127.08%	125.08%	109.31\%	100.29%	124.15%	116.67%
$\overline{2}$	112.85%	103.46%	118.27%	116.22%	103.93%	94.75%	116.18%	108.51%
	72.92%	62.35\%	69.43%	67.10\%	66.34\%	56.11\%	70.86\%	62.08%
$\mathbb{E}\left[r_L\right]$	100%	90.20%	100%	97.79%	100%	90.68%	100%	91.90%

 TABLE 5 OPTIMAL RELATIVITIES FOR THE BMS

Future research

- how the varying extent of *a priori* classification affects the choice of sufficiently effective transition rules
- Gilde and Sundt (1989): linear relativities

Q&A

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