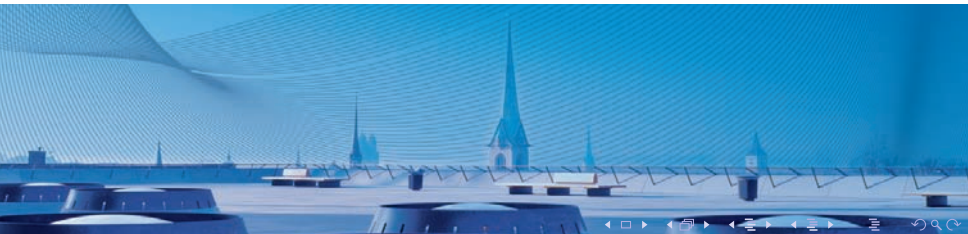


Development Pattern and Prediction Error for the Stochastic Bornhuetter-Ferguson Claims Reserving Method

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Overview

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- 2 Bornhuetter-Ferguson Method (BF)
- 3 Normal Model
- 4 Estimation of the Parameters and their Correlations
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Notation

- Accident years i , $0 \leq i \leq I$

Table: Claims development triangle

accident year i	development year j				
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- Goal: Predict $\mathcal{D}_I^c = \{X_{i,j}; i+j > I, i \leq I, j \leq J\}$

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BF predictor for the outstanding loss liabilities (IBNR and IBNeR in case of incurred claims data) $R_i = C_{i,J} - C_{i,I-i}$ at time I

$$\hat{R}_i = \hat{\mu}_i(1 - \hat{\beta}_{I-i}),$$

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- Assumption of a cross-classified model $E[X_{i,j}] = \mu_i \gamma_j$

Motivation for the Estimation of the Pattern

- Often the chain ladder (CL) development pattern is used for $\hat{\gamma}_j$

$$\hat{\gamma}_j^{CL} = \prod_{k=j}^{J-1} \hat{f}_k^{-1} - \prod_{k=j-1}^{J-1} \hat{f}_k^{-1}, \quad \hat{f}_k = \frac{\sum_{i=0}^{I-k-1} C_{i,k+1}}{\sum_{i=0}^{I-k-1} C_{i,k}}.$$

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- If the μ_i were known then the best linear unbiased estimate of γ_j would be

$$\gamma_j^{(0)} = \frac{\sum_{i=0}^{I-j} X_{i,j}}{\sum_{i=0}^{I-j} \mu_i}, \quad 0 \leq j \leq J.$$

⇒ A first candidate is the raw estimate

$$\hat{\gamma}_j^{(0)} = \frac{\sum_{i=0}^{I-j} X_{i,j}}{\sum_{i=0}^{I-j} \hat{\mu}_i},$$

However, they do not sum up to 1.

Intuitive Estimation of the Pattern

- If the full rectangle was known an obvious estimate is given by

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- If only the upper trapezoid and the μ_i are known, replace the unknown $X_{i,j}$ by predictors $\mu_i \hat{\gamma}_j$

$$\hat{\gamma}_j = \frac{\sum_{i=0}^{I-j} X_{i,j} + \sum_{i=I-j+1}^I \mu_i \hat{\gamma}_j}{\sum_{i=0}^{I-J} C_{i,J} + \sum_{i=I-J+1}^I \left(C_{i,I-i} + \sum_{l=I-i+1}^J \mu_i \hat{\gamma}_l \right)}, \quad 0 \leq j \leq J.$$

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- In an over-dispersed Poisson model the maximum likelihood estimates (MLE's) satisfy these equations.

Normal Model

Model Assumptions (Normal Model)

- N1** The $X_{i,j}$ are independent and normally distributed and there exist parameters $\mu_0, \mu_1, \dots, \mu_I$ and $\gamma_0, \gamma_1, \dots, \gamma_J$ with $\sum_{j=0}^J \gamma_j = 1$ and $\sigma_0^2, \dots, \sigma_J^2$ such that

$$E[X_{i,j}] = \mu_i \gamma_j,$$
$$\text{Var}(X_{i,j}) = \mu_i \sigma_j^2,$$

where $\sigma_j^2 > 0, 0 \leq j \leq J$.

- N2** The a priori estimates $\hat{\mu}_i$ for $\mu_i = E[C_{i,J}]$ are unbiased and independent of all $X_{l,j}$.

Maximum Likelihood Estimation (MLE) of the γ_j 's

- We calculate the MLE's assuming that the true μ_i 's and σ_j^2 's are known and then replace the μ_i 's by the a priori estimates $\hat{\mu}_i$ and the σ_j^2 's by estimates $\hat{\sigma}_j^2$.

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- In the Normal Model we obtain

$$\hat{\gamma}_j = \underbrace{\frac{\sum_{i=0}^{I-j} X_{i,j}}{\sum_{i=0}^{I-j} \hat{\mu}_i}}_{\text{raw estimate}} + \underbrace{\frac{\hat{\sigma}_j^2 / \sum_{i=0}^{I-j} \hat{\mu}_i}{\sum_{l=0}^J \left(\hat{\sigma}_l^2 / \sum_{i=0}^{I-l} \hat{\mu}_i \right)} \left(1 - \sum_{l=0}^J \frac{\sum_{i=0}^{I-l} X_{i,l}}{\sum_{i=0}^{I-l} \hat{\mu}_i} \right)}_{\text{correction term}},$$

where

$$\hat{\sigma}_j^2 = \frac{1}{I-j} \sum_{i=0}^{I-j} \hat{\mu}_i \left(\frac{X_{i,j}}{\hat{\mu}_i} - \frac{\sum_{i=0}^{I-j} X_{i,j}}{\sum_{i=0}^{I-j} \hat{\mu}_i} \right)^2, \quad 0 \leq j \leq J, \quad j \neq I.$$

Covariance matrix of the $\hat{\gamma}_j$'s

We use the asymptotic properties of MLE's (Fisher Information matrix) to estimate the covariance matrix of the $\hat{\gamma}_j$'s.:

$$\widehat{\text{Cov}}(\hat{\gamma}_j, \hat{\gamma}_k) = \frac{\hat{\sigma}_j^2}{\sum_{i=0}^{I-j} \hat{\mu}_i} \left(\mathbb{1}_{\{j=k\}} - \frac{\left(\hat{\sigma}_k^2 / \sum_{i=0}^{I-k} \hat{\mu}_i \right)}{\sum_{l=0}^J \left(\hat{\sigma}_l^2 / \sum_{i=0}^{I-l} \hat{\mu}_i \right)} \right).$$

Remarks:

- For the best linear unbiased estimate $\gamma_j^{(0)}$ (in the case of known μ_i) we have

$$\text{Cov}(\gamma_j^{(0)}, \gamma_k^{(0)}) = \mathbb{1}_{\{j=k\}} \frac{\sigma_j^2}{\sum_{i=0}^{I-j} \mu_i},$$

(compare with first summand).

- Because of the side constraint $\sum_{j=0}^J \gamma_j = 1$ the off-diagonal correlations must be negative (compare with second summand).

Prediction Uncertainty

Given all information \mathcal{I}_I (i.e. \mathcal{D}_I and all $\hat{\mu}_i$), the conditional MSE of the predictor $\hat{R}_i = \hat{\mu}_i(1 - \hat{\beta}_{I-i})$ is given by

$$\begin{aligned} \text{mse}_{R_i|\mathcal{I}_I}(\hat{R}_i) &= E \left[\left(R_i - \hat{R}_i \right)^2 \middle| \mathcal{I}_I \right] \\ &= E \left[\left(\sum_{j=I-i+1}^J X_{i,j} - \hat{\mu}_i(1 - \hat{\beta}_{I-i}) \right)^2 \middle| \mathcal{I}_I \right] \\ &= \underbrace{\sum_{j=I-i+1}^J \text{Var}(X_{i,j})}_{\text{Process Variance (PV}_i)} + \underbrace{\left(\hat{\mu}_i(1 - \hat{\beta}_{I-i}) - \mu_i(1 - \beta_{I-i}) \right)^2}_{\text{Estimation Error (EE}_i)}. \end{aligned}$$

MSEP

We estimate the conditional MSEP given \mathcal{I}_I as follows

$$\widehat{\text{mse}}_{R_i|\mathcal{I}_I}(\widehat{R}_i) = \sum_{j=I-i+1}^J \widehat{\text{Var}}(X_{i,j}) + \widehat{\text{Var}}(\widehat{\mu}_i)(1 - \widehat{\beta}_{I-i})^2 + \widehat{\mu}_i^2 \left(\sum_{j=0}^{I-i} \widehat{\text{Var}}(\widehat{\gamma}_j) + 2 \sum_{0 \leq j < k \leq I-i} \widehat{\text{Cov}}(\widehat{\gamma}_j, \widehat{\gamma}_k) \right),$$

$$\widehat{\text{mse}}_{\sum_{i=I-J+1}^I R_i|\mathcal{I}_I} \left(\sum_{i=I-J+1}^I \widehat{R}_i \right) = \sum_{i=I-J+1}^I \widehat{\text{mse}}_{R_i|\mathcal{I}_I}(\widehat{R}_i) + 2 \sum_{I-J+1 \leq i < k \leq I} \left((1 - \widehat{\beta}_{I-i})(1 - \widehat{\beta}_{I-k}) \widehat{\text{Cov}}(\widehat{\mu}_i, \widehat{\mu}_k) + \widehat{\mu}_i \widehat{\mu}_k \sum_{j=0}^{I-i} \sum_{l=0}^{I-k} \widehat{\text{Cov}}(\widehat{\gamma}_j, \widehat{\gamma}_l) \right).$$

Conclusions and Remarks

Under distributional assumptions we have derived

- estimates for the development pattern taking all relevant information into account
- formulas for the smoothing from the raw estimates $\hat{\gamma}_j^{(0)}$ to the final estimates $\hat{\gamma}_j$
- estimates for the correlations of these estimates.

We recommend to use these formulas also in the distribution-free case (currently there are no estimators available from which we know that they perform better).